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By Hong Cheng

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A prototype autonomous vehicle and its algorithms for lane detection. Intelligent Vehicles Symposium, Autonomous Intelligent Vehicles: Theory,

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Hong Cheng is a full Professor in He received Ph.D degree in Pattern Recognition and Intelligent Systems and Autonomous Intelligent Vehicles: Theory

Cheng H. Autonomous Intelligent Vehicles. Theory, -

Springer, 2011, -163 pp. Over the years, the field of intelligent vehicles has become a major research theme in intelligent transportation

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Algorithms; Autonomous intelligent cruise control; Delays; Game theory; Intelligent vehicles; Intersections; Optimization; Unsignalized intersections. Subject Areas:

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laser scanner. In: IEEE Intelligent Vehicles Principles of Robot Motion: Theory, Algorithms and Detection of Autonomous Transport Vehicles

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